

# AN30259C

http://www.semicon.panasonic.co.jp/en/

# 3-ch. LED Driver for illumination

#### FEATURES

- I<sup>2</sup>C Interface (Slave address is switchable.)
- Built-in 3-ch. LED Driver Circuit
  (Max Current Selectable [63.75 mA / 31.875 mA / 25.50 mA / 12.75 mA])
- 2.4 MHz OSC
- 12 pin Wafer level chip size package (WLCSP)

#### DESCRIPTION

AN30259A has 3-ch. LED Driver, suitable for RGB illumination. By synchronous clock function, simultaneous LED turn ON/OFF operation of up to 4 ICs can be achieved.

#### **APPLICATIONS**

- Mobile Phone
- Smart Phone
- PCs
- Game Consoles
- Home Appliances etc.

# TYPICAL APPLICATION

TOP VIEW



#### Note)

This application circuit is an example. The operation of the mass production set is not guaranteed. Customers shall perform enough evaluation and verification on the design of mass production set. Customers shall be fully responsible for the incorporation of the above application circuit and information in the design of the equipment.



#### **ABSOLUTE MAXIMUM RATINGS**

Parameter	Symbol	Rating	Unit	Note
Supply voltage	VCC <sub>MAX</sub>	7.0	V	*1
Supply voltage	VDD <sub>MAX</sub>	4.6	V	*1
Operating ambience temperature	T <sub>opr</sub>	–30 to + 85	°C	*2
Operating junction temperature	Tj	– 30 to + 125	°C	*2
Storage temperature	T <sub>stg</sub>	– 55 to + 125	°C	*2
Input Voltage Range	ADSEL1, ADSEL2, SCL, SDA, CLKPWM - 0.3 to 4.3		V	_
Output Voltage Range	LED1, LED2, LED3	– 0.3 to 6.5	v	
ESD	HBM (Human Body Model)	2.0	kV	

Note) This product may sustain permanent damage if subjected to conditions higher than the above stated absolute maximum rating. This rating is the maximum rating and device operating at this range is not guaranteeable as it is higher than our stated recommended operating range. When subjected under the absolute maximum rating for a long time, the reliability of the product may be affected.

#### POWER DISSIPATION RATING

PACKAGE	$\theta_{JA}$	Р <sub>D</sub> (Та=25 °С)	Р <sub>D</sub> (Та=85 °С)
12 pin Wafer Level Chip Size Package (WLCSP)	537.1 °C /W	0.186 W	0.074 W

Note) For the actual usage, please refer to the P<sub>D</sub>-Ta characteristics diagram in the package specification, supply voltage, load and ambient temperature conditions to ensure that there is enough margin follow the power and the thermal design does not exceed the allowable value.



#### **CAUTION**

Although this IC has built-in ESD protection circuit, it may still sustain permanent damage if not handled properly. Therefore, proper ESD precautions are recommended to avoid electrostatic damage to the MOS gates

<sup>\*1:</sup> VCC<sub>MAX</sub> = VCC, VDD<sub>MAX</sub> = VDD, the values under the condition not exceeding the above absolute maximum ratings and the power dissipation.

<sup>\*2:</sup> Except for operating ambient temperature, operating junction temperature and storage temperature, all ratings are for T<sub>a</sub> = 25°C.



## **RECOMMENDED OPERATING CONDITIONS**

Parameter	Symbol	Min.	Тур.	Max.	Unit	Note
Supply voltage range	VCC	3.1	3.7	6.0	V	_
	VDD	1.7	1.85	3.2	V	_
Input Voltage Range	- 0.3		VDD + 0.3	V	*1	
Output Voltage Range	LED1, LED2, LED3	- 0.3		VCC + 0.3	V	*1

Note) Voltage values, unless otherwise specified, are with respect to GND. GND is voltage for GND. VDD is voltage for VDD. VCC is voltage for VCC.

\*1 : ( VDD + 0.3 ) V must not be exceeded 4.6 V. ( VCC + 0.3 ) V must not be exceeded 7 V.



## **ELECTRICAL CHARACTERISTICS**

 $V_{CC}$  = 3.6 V,  $V_{DD}$  = 1.8 V

Note)  $T_a = 25 \text{ °C} \pm 2 \text{ °C}$  unless otherwise specified.

Devenenter	Gumbal	Condition		Limits		Unit	Nata
Parameter	Symbol	Condition	Min	Тур	Max	Unit	Note
Current consumption							
Current consumption 1 OFF mode	I <sub>CC1</sub>	V <sub>DD</sub> = 0 V		0	2	μA	_
Current consumption 2 OFF mode	I <sub>CC2</sub>	V <sub>DD</sub> = 1.8 V		1	5	μA	_
Current consumption 3 LED lighting mode				0.6	1.0	mA	_
LED Driver	·						
Off time leak current	I <sub>LEAK</sub>	Off setting V <sub>LED1 to 3</sub> = 6.0 V			1.0	μA	_
Minimum setting current value 1	I <sub>MIN1</sub>	IMAX[1:0] = 01, V <sub>LED1 to 3</sub> = 1.0 V	0.05	0.10	0.15	mA	_
Minimum setting current value 2	I <sub>MIN2</sub>	IMAX[1:0] = 01, V <sub>LED1 to 3</sub> = 1.0 V	0.736	0.80	0.864	mA	_
Maximum setting current value	I <sub>MAX</sub>	IMAX[1:0] = 01, V <sub>LED1 to 3</sub> = 1.0 V	23.46	25.50	27.54	mA	_
Current step	I <sub>STEP</sub>	IMAX[1:0] = 01, V <sub>LED1 to 3</sub> = 1.0 V	0.00	0.10	0.18	mA	_
Minimum voltage for retainable constant current value	retainable constant current V <sub>SAT</sub>		_	0.2	0.4	V	_
Error between channels	Error between channels $I_{MATCH}$ $I_{2.80 mA setting,}$ $V_{LED1 to 3} = 1.0 V$		-5		5	%	_
Internal oscillator		1	1	1		1	
Oscillation frequency	f <sub>osc</sub>	_	1.92	2.40	2.88	MHz	_

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## **ELECTRICAL CHARACTERISTICS (continued)**

 $V_{CC}$  = 3.6 V,  $V_{DD}$  = 1.8 V

Note) T<sub>a</sub> = 25 °C  $\pm$  2 °C unless otherwise specified.

Deverseden	Question	Condition		Limits		L lusit	Nata
Parameter	Symbol	Condition	Min	Тур	Max	Unit	Note
SCL, SDA							
High-level input voltage range	V <sub>IH1</sub>	Voltage which recognized that SDA and SCL are High-level	$V_{DD} \times 0.7$	_	V <sub>DD</sub> + 0.5	V	*1
Low-level input voltage range	V <sub>IL1</sub>	Voltage which recognized that SDA and SCL are Low-level	- 0.5		$V_{DD} \times 0.3$	V	*1
High-level input current	I <sub>IH1</sub>	V <sub>SDA</sub> ,V <sub>SCL</sub> = 1.8 V	_	0	1	μA	-
Low-level input current	I <sub>IL1</sub>	V <sub>SDA</sub> ,V <sub>SCL</sub> = 0 V	_	0	1	μA	-
Low-level output voltage1 (SDA)	V <sub>OL1H</sub>	I <sub>SDA</sub> = 3 mA, V <sub>DD</sub> > 2 V	0		0.4	V	-
Low-level output voltage2 (SDA)	V <sub>OL1L</sub>	$I_{SDA}$ = 3 mA, $V_{DD}$ < 2 V	0	_	$0.2 \times V_{DD}$	V	_
SCL clock frequency	f <sub>SCL</sub>	_	0	_	400	kHz	-
CLKPWM							
High-level input voltage range	V <sub>IH2</sub>	_	V <sub>DD</sub> × 0.7		V <sub>DD</sub> + 0.2	V	_
Low-level input voltage range	V <sub>IL2</sub>	_	- 0.2	_	$V_{DD} \times 0.3$	V	_
Pin pull down resistance value	R <sub>PD2</sub>	_	0.5	1.0	2.0	MΩ	-
High-level output voltage	V <sub>OH2</sub>	I <sub>CLKPWM</sub> = – 2 mA	V <sub>DD</sub> × 0.8		V <sub>DD</sub> + 0.2	V	-
Low-level output voltage	V <sub>OL2</sub>	I <sub>CLKPWM</sub> = 2 mA	-0.2	_	V <sub>DD</sub> × 0.2	V	-
ADSEL1, ADSEL2		1					<u> </u>
High-level input voltage range	V <sub>IH3</sub>	_	V <sub>DD</sub> × 0.7		V <sub>DD</sub> + 0.2	V	_
Low-level input voltage range	V <sub>IL3</sub>	_	- 0.2	_	$V_{DD} \times 0.3$	V	_
High-level input current	I <sub>IH3</sub>	V <sub>ADSEL1, 2</sub> = 1.8 V		0	1	μA	_
Low-level input current	I <sub>IL3</sub>	$V_{ADSEL1, 2} = 0 V$	_	0	1	μA	_

Note)\*1: The input threshold voltage of I<sup>2</sup>C bus (Vth) is linked to V<sub>DD</sub> (I<sup>2</sup>C bus I/O stage supply voltage).

In case the pull-up voltage is not  $V_{DD}$ , the threshold voltage (Vth) is fixed to (( $V_{DD}$  / 2) ± (Schmitt width) / 2) and High-level, Low-level of input voltage are not specified.

In this case, pay attention to Low-level (max.) value (V $_{\rm ILmax}).$ 

It is recommended that the pull-up voltage of  $I^{2}C$  bus is set to the  $I^{2}C$  bus I/O stage supply voltage (V<sub>DD</sub>).



## **ELECTRICAL CHARACTERISTICS (continued)**

 $V_{CC}$  = 3.6 V,  $V_{DD}$  = 1.8 V

Note)  $~~T_a$  = 25  $^{\circ}C \pm$  2  $^{\circ}C$  unless otherwise specified.

	Paramotor	Symbol Condition			Limits			
Parameter		Symbol	Condition	Min	Тур	Max	Unit	Note
CL	KPWM							
	External PWM operation mode Possible input high pulse width	W <sub>PWM</sub>	—		2.5		μS	*2

Note) \*2 : Typical design value



## **ELECTRICAL CHARACTERISTICS (continued)**

 $V_{CC}$  = 3.6 V,  $V_{DD}$  = 1.8 V

Note) T<sub>a</sub> = 25 °C  $\pm$  2 °C unless otherwise specified.

Devemeter	Symbol	Condition		Limits		Unit	Nata		
Parameter	Symbol	Condition	Min	Тур	Max	Unit	Note		
<sup>2</sup> C bus (Internal I/O stage characteris	tics)								
Input voltage hysteresis (1)	age hysteresis (1) V <sub>hys1</sub> volta		teresis (1) V <sub>hys1</sub> SCL, SDA hysteresis voltage VDD > 2 V		$0.05 \times V_{DD}$	_	_	v	*3
Input voltage hysteresis (2)	V <sub>hys2</sub>	SCL, SDA hysteresis voltage VDD < 2 V	$0.1 \times V_{DD}$	_	_	v	*3		
Output fall time from $V_{IHmin}$ to $V_{ILmax}$	t <sub>of</sub>	Bus capacitance : 10 pF to 400pF $I_P \le 6$ mA (V <sub>OLmax</sub> = 0.6 V) $I_P$ : Max. sink current	20 + 0.1×C <sub>b</sub>	_	250	ns	*3		
Spike pulse width kept down by input filter	t <sub>sp</sub>	_	0	_	50	ns	*3		
I/O pin capacitance	C <sub>i</sub>	—	_		10	pF	*3		

Notes ) \*3 : These are values checked by design but not production tested.



#### **ELECTRICAL CHARACTERISTICS (continued)**

 $V_{CC}$  = 3.6 V,  $V_{DD}$  = 1.8 V

Note) T<sub>a</sub> = 25 °C  $\pm$  2 °C unless otherwise specified.

	Devenenter	Cumb al	Condition		Limits		L los it	Nata
	Parameter	Symbol	Condition	Min	Тур	Max	Unit	Note
I <sup>2</sup> C	bus (Bus line specifications)							
	Hold duration (recursive)	t <sub>HD:STA</sub>	After $t_{HD:STA,.}$ the first clock pulse is generated.	0.6	—		μS	*3,4
	SCL clock "L" duration	t <sub>LOW</sub>	—	1.3	—	_	μS	*3,4
	SCL clock "H" duration	t <sub>HIGH</sub>	—	0.6	_	_	μS	*3,4
	Recursive "START" condition setting time	t <sub>su:sta</sub>	_	0.6	—	_	μS	*3,4
	Data hold time	t <sub>HD:DAT</sub>	_	0	_	0.9	μS	*3,4
	Data setup time	t <sub>SU:DAT</sub>	—	100		_	ns	*3,4
	SDA, SCL signal rise up time	t <sub>r</sub>	—	20 + 0.1×C <sub>b</sub>	—	300	ns	*3,4
	SDA, SCL signal fall time	t <sub>f</sub>	_	20 + 0.1×C <sub>b</sub>	_	300	ns	*3,4
	Setup time under "STOP" condition	t <sub>su:sto</sub>	_	0.6	—	_	μS	*3,4
	Bus free time between under "STOP" condition and "START" condition	t <sub>BUF</sub>	—	1.3	—		μS	*3,4
	Capacitive load for each bus line	C <sub>b</sub>	—	—	—	400	pF	*3,4
	Noise margin of each connection device at Low-level	V <sub>nL</sub>	—	$0.1 \times V_{DD}$		_	V	*3,4
	Noise margin of each connection device at High-level	V <sub>nH</sub>	_	$0.2 \times V_{DD}$	_		V	*3,4

Note) \*3: These are values checked by design but not production tested.

\*4: The timing of Fast-mode devices in l<sup>2</sup>C-bus is specified as follows. All values referred to  $V_{\rm IHmin}$  and  $V_{\rm ILmax}$  level.



S: START condition

Sr : Repeat START condition

P: STOP condition



## **PIN CONFIGURATION**



## **PIN FUNCTIONS**

Pin No.	Pin name	Туре	Description
A1	IREF	Output	Resistor connection pin for setting constant current value
A2	VCC	Power Supply	Power supply pin for LED Circuit
A3	CLKPWM	Input/Output	Reference clock Input / Output pin PWM signal input pin to control LED brightness by the external pulse signal
A4	LED3	Output	LED3 output pin
B1	ADSEL2	Input	I <sup>2</sup> C Interface slave address switch pin 2
B2	ADSEL1	Input	I <sup>2</sup> C Interface slave address switch pin 1
B3	GND	Ground	Ground pin
B4	LED2	Output	LED2 output pin
C1	SDA	Input/Output	I <sup>2</sup> C interface data Input / Output pin
C2	SCL	Input	I <sup>2</sup> C interface clock input pin
C3	VDD	Power Supply	Power supply pin for interface
C4	LED1	Output	LED1 output pin



## FUNCTIONAL BLOCK DIAGRAM



Note) This block diagram is for explaining functions. Part of the block diagram may be omitted, or it may be simplified.



#### OPERATION

#### 1. I<sup>2</sup>C-bus Interface

- 1) Basic Rules
- This LSI, I<sup>2</sup>C-bus, is designed to correspond to the Standard-mode (100 kbps) and Fast-mode(400 kbps) devices in the version 2.1 of NXP's specification. However, it does not correspond to the H<sub>S</sub>-mode (to 3.4 Mbps).
- This LSI will be operated as a slave device in the I<sup>2</sup>C-bus system. This IC will not operate as a master device.
- The program operation check of this LSI has not been conducted on the multi-master bus system and the mix-speed bus system, yet. The connected confirmation of this LSI to the CBUS receiver also has not been checked. Please confirm with our company if it will be used in these mode systems. The I<sup>2</sup>C is the brand of NXP.
- 2) START and STOP conditions

A High to Low transition on the SDA line while SCL is High is one such unique case. This situation indicates START condition. A Low to High transition on the SDA line while SCL is High defines STOP condition. START and STOP conditions are always generated by the master. After START condition occurs, the bus will be busy. The bus is considered to be free again a certain time after the STOP condition.



3) Transferring Data

Every byte put on the SDA line must be 8-bits long. The number of bytes that can be transmitted per transfer is unrestricted. Each byte has to be followed by an acknowledge bit. Data is transferred with the most significant bit (MSB) first.





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## **OPERATION** (continued)

#### 1. I<sup>2</sup>C-bus Interface (continued)

4) Data format

Slave address can be switched by ADSEL1, ADSEL2 pin connections. The chart on the right shows the slave address of this product.

ADSEL2	ADSEL1	Slave address			
Low (Ground)	Low (Ground)	30 h (0110000)			
Low (Ground)	High (VDD)	31 h (0110001)			
High (VDD)	Low (Ground)	32 h (0110010)			
High (VDD)	High (VDD)	33 h (0110011)			



#### Read mode

A) When sub-address is not assigned.

When data is read without assigning sub-address, it is possible to read the value of sub-address specified in Write mode immediately before.



Ex) When writing data into address and reading data from "01 h"



Sub-address should be assigned first.



#### 1. I<sup>2</sup>C-bus Interface (continued)

- 4) Data format (continued)
- Continuous Write mode

When using the continuous Write mode, the most significant bit of Sub address should be set to [1].



B) When Sub address is specified



Sub address is specified initially



#### 2. Register map

Sub	-	Register		_		_	Data	_	_		
Addr ess	R/W	Name	D7	D6	D5	D4	D3	D2	D1	D0	
00h	W	SRESET	_							SRESET	
01h	R/W	LEDON	_	LED3MD	LED2MD	LED1MD		LED3ON	LED2ON	LED1ON	
02h	R/W	SEL	IMA	X [1:0]	IOEN	CLKDIR	EXTPWM	DLYSEL3	DLYSEL2	DLYSEL1	
03h	R/W	LED1CC		LED1CC [7:0]							
04h	R/W	LED2CC				LEC	02CC [7:0]				
05h	R/W	LED3CC				LEC	03CC [7:0]				
06h	R/W	LED1SLP		SLP1TT2 [3:0] SLP1TT1 [3:0]							
07h	R/W	LED2SLP		SLP2	TT2 [3:0]		SLP2TT1 [3:0]				
08h	R/W	LED3SLP		SLP3	TT2 [3:0]			SLP3T	Г1 [3:0]		
09h	R/W	LED1CNT1		DUTYN	MAX1 [3:0]			DUTYMI	D1 [3:0]		
0Ah	R/W	LED1CNT2		DELA	AY1 [3:0]			DUTYMI	N1 [3:0]		
0Bh	R/W	LED1CNT3		SLP1	DT2 [3:0]		SLP1DT1 [3:0]				
0Ch	R/W	LED1CNT4		SLP1	DT4 [3:0]		SLP1DT3 [3:0]				
0Dh	R/W	LED2CNT1		DUTYN	MAX2 [3:0]		DUTYMID2 [3:0]				
0Eh	R/W	LED2CNT2		DELA	AY2 [3:0]			DUTYMI	N2 [3:0]		
0Fh	R/W	LED2CNT3		SLP2	DT2 [3:0]			SLP2D	T1 [3:0]		
10h	R/W	LED2CNT4		SLP2	DT4 [3:0]			SLP2D	T3 [3:0]		
11h	R/W	LED3CNT1	DUTYMAX3 [3:0]				DUTYMID3 [3:0]				
12h	R/W	LED3CNT2		DELAY3 [3:0]				DUTYMIN3 [3:0]			
13h	R/W	LED3CNT3		SLP3	DT2 [3:0]		SLP3DT1 [3:0]				
14h	R/W	LED3CNT4		SLP3	DT4 [3:0]			SLP3D	ГЗ [3:0]		

Note) Read value in "-" is [0].



#### 3. Register map details

Register Name      SRESET						SET			
Address	R / W mode	D7	D7 D6 D5			D3	D2	D1	D0
00 h	W					—		_	SRESET
Default	00 h	0	0	0	0	0	0	0	0

#### D0 : Software reset pin

[0] : Normal condition ( default )

[1] : Reset (Reset all the other register and returns to Low automatically)



#### 3. Register map details (continued)

Registe	r Name	LEDON								
Address	R / W mode	D7	D6	D5	D4	D3	D2	D1	D0	
01 h	R/W	_	LED3MD	LED2MD	LED1MD	_	LED3ON	LED2ON	LED1ON	
Default	00 h	0	0	0	0	0	0	0	0	

#### D6 : LED3MD LED3 lighting mode setting

[0] : LED3 constant current mode ( default )

- [1] : LED3 slope mode
- D5 : LED2MD LED2 lighting mode setting
  - [0] : LED2 constant current mode ( default )
  - [1] : LED2 slope mode
- D4 : LED1MD LED1 lighting mode setting [0] : LED1 constant current mode ( default )
  - [1] : LED1 slope mode
- D2 : LED3ON LED3 enable control [0] : LED3 OFF ( default ) [1] : LED3 ON
- D1 : LED2ON LED2 enable control [0] : LED2 OFF ( default ) [1] : LED2 ON
- D0 : LED1ON LED1 enable control [0] : LED1 OFF ( default ) [1] : LED1 ON

LED1 operation mode

D4	D0	LED1 exercises mode
LED1MD	LED1ON	LED1 operation mode
0	0	OFF
1	0	OFF
0	1	ON (constant current mode)
1	1	ON (slope mode)

This mode applies to LED2, LED3 operation modes, too.



#### 3. Register map details (continued)

Registe	er Name		SEL									
Address	R / W mode	D7	D7 D6		D4	D3	D2	D1	D0			
02 h	R/W	IMAX	IMAX [1:0]		CLKDIR	EXTPWM	DLYSEL3	DLYSEL2	DLYSEL1			
Default	40 h	0 1		0	0	0	0	0	0			

D7-6 : IMAX [1:0] Maximum value, Step value setting for current setting

[00] : Maximum value 12.75 mA, Step value 0.05 mA

[01] : Maximum value 25.50 mA, Step value 0.10 mA ( default )

[10] : Maximum value 31.875 mA, Step value 0.125 mA

- [11] : Maximum value 63.75 mA, Step value 0.25 mA
- D5 : IOEN CLKPWM pin enable control [0] : CLKPWM pin invalid ( default ) [1] : CLKPWM pin valid

D4 : CLKDIR CLKPWM pin I/O mode setting [0] : CLKPWM pin input mode ( default )

- [1] : CLKPWM pin output mode
- D3 D5 D4 **CLKPWM** operation mode (Clock mode/PWM mode) **CLKDIR EXTPWM** IOEN 0 0 or 1 0 or 1 OFF 1 0 or 1 1 External PWM operation mode 1 0 0 External clock input mode 1 1 0 Internal clock output mode
- D3 : EXTPWM CLKPWM pin PWM mode setting

[0] : CLKPWM pin PWM mode invalid ( default )

[1] : CLKPWM pin PWM mode valid

- D2 : DLYSEL3 Lighting delay time mode setting at LED3 Slope mode
  - [0] : LED3 delay time Max 7.50 s mode ( default )

[1] : LED3 delay time Max 1.86 s mode

D1 : DLYSEL2 Lighting delay time mode setting at LED2 Slope mode

[0]: LED2 Delay time Max 7.50 s mode ( default )

[1] : LED2 Delay time Max 1.86 s mode

D0 : DLYSEL1 Lighting delay time mode setting at LED1 Slope mode

[0]: LED1 Delay time Max 7.50 s mode ( default )

[1] : LED1 Delay time Max 1.86 s mode

Please refer to the detail explanation of following register DELAY1 for DLYSEL\* details.

<External PWM operation mode>

LED lighting turns ON/OFF by High/Low setting of CLKPWM pin at the time of LED lighting setting.

This mode enables LED lighting synchronization with music signal and brightness control by High/Low Duty ratio.

<External clock input mode>

The reference clock for Slope control is CLKPWM pin. Synchronization with external signals is possible.

<Internal clock output mode>

Internal reference clock for Slope control is generated via CLKPWM pin.

(The output clock will not be available when LED1ON=LED2ON=LED3ON=0.)

Synchronized operation can be possible when more than two pieces of this LSI are connected.



#### 3. Register map details (continued)

Registe	er Name	LED1CC								
Address	R / W mode	D7	D7 D6 D5 D4 D3 D2 D1							
03 h	R/W				LED1C	C [7 : 0]				
Default	00 h	0	0 0 0 0 0 0 0 0							

D7-0 : LED1CC [7: 0] Current setting for LED1 constant current output

Registe	r Name	LED2CC									
Address	R / W mode	D7	D7 D6 D5 D4 D3 D2 D1						D0		
04 h	R/W		LED2CC [7 : 0]								
Default	00 h	0	0 0 0 0 0 0 0 0								

D7-0 : LED2CC [7: 0] Current setting for LED2 constant current output

Registe	r Name		LED3CC									
Address	R / W mode	D7	D6	D5	D4	D3	D2	D1	D0			
05 h	R/W				LED3C0	C [7 : 0]						
Default	00 h	0	0 0 0 0 0 0 0 0									

D7-0 : LED3CC [7 : 0] Current setting for LED3 constant current output

Output current value can be changed by IMAX setting as below.

		L	ED*C	C [7 : 0	)]				IMAX	[1:0]	
D7	D6	D5	D4	D3	D2	D1	D0	00h	01h	10h	11h
0	0	0	0	0	0	0	0	0.000 mA	0.000 mA	0.000 mA	0.000 mA
0	0	0	0	0	0	0	1	0.050 mA	0.100 mA	0.125 mA	0.250 mA
0	0	0	0	0	0	1	0	0.100 mA	0.200 mA	0.250 mA	0.500 mA
:	:	:	:	:	:	:	:	:	:	:	:
:	:	:	:	:	:	:	:	0.050 mA	0.100 mA	0.125 mA	0.250 mA
:	:	:	:	:	:	:	:	Step	Step	Step	Step
:	:	:	:	:	:	:	:	:	:	:	:
1	1	1	1	1	1	1	0	12.700 mA	25.400 mA	31.750 mA	63.500 mA
1	1	1	1	1	1	1	1	12.750 mA	25.500 mA	31.875 mA	63.750 mA



#### 3. Register map details (continued)

Registe	er Name		LED1SLP								
Address	R / W mode	D7	D6	D5	D4	D3	D2	D1	D0		
06 h	R/W		SLP1T1	2 [3 : 0]		SLP1TT1 [3 : 0]					
Default	88 h	1	0	0	0	1	0	0	0		

Total time of SLOPE operation for LED1 will be set.

Please refer to following "4. LED control Slope lighting mode" for the details of slope operation.

	SLP1TT	1 [3:0]		Total time of SLOPE operation 1, 2
0	0	0	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 0 = 0.0 s
0	0	0	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 1 = 0.5 s
0	0	1	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 2 = 1.0 s
:	:	:	:	:
:	:	:	:	0.5 s Step
:	:	:	:	:
1	1	0	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 12 = 6.0 s
1	1	0	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 13 = 6.5 s
1	1	1	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 14 = 7.0 s
1	1	1	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 15 = 7.5 s

SLP1TT1 [3:0] is set as the chart below shows.

SLP1TT2 [3: 0] is set as the chart below shows.

	SLP1TT	2 [3:0]		Total time of SLOPE operation 3, 4
0	0	0	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 0 = 0.0 s
0	0	0	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 1 = 0.5 s
0	0	1	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 2 = 1.0 s
:	:	:	:	:
:	:	:	:	0.5 s Step
:	:	:	:	:
1	1	0	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 12 = 6.0 s
1	1	0	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 13 = 6.5 s
1	1	1	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 14 = 7.0 s
1	1	1	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 125 $\times$ 15 = 7.5 s



#### 3. Register map details (continued)

Registe	er Name	LED2SLP								
Address	R / W mode	D7	D6	D5	D4	D3	D2	D1	D0	
07 h	R/W		SLP2TT	2 [3 : 0]		SLP2TT1 [3 : 0]				
Default	88 h	1	0	0	0	1	0	0	0	

Total time of Slope operation for LED2 will be set.

Registe	r Name	LED3SLP								
Address	R / W mode	D7	D6	D5	D4	D3	D2	D1	D0	
08 h	R/W		SLP3T1	2 [3 : 0]		SLP3TT1 [3 : 0]				
Default	88 h	1	0	0	0	1	0	0	0	

Total time of Slope operation for LED3 will be set.

Please refer to following "4. LED control Slope lighting mode " for the details of slope operation.

The Slope setting charts for LED2 and LED3 are the same as the one for LED1 in the previous page.



#### 3. Register map details (continued)

Registe	r Name	LED1CNT1							
Address	R / W mode	D7	D6	D5	D3	D2	D1	D0	
09 h	R/W		DUTYMA	X1 [3 : 0]		DUTYMID1 [3 : 0]			
Default	F8 h	1	1 1 1 1 1 0						0

D7-4 : DUTYMAX1 [3 : 0] LED1 at Slope lighting maximum PWM Duty setting

D3-0 : DUTYMID1 [3 : 0] LED1 at Slope lighting middle PWM Duty setting

Registe	r Name	LED1CNT2							
Address	R / W mode	D7	D7 D6 D5 D4 D3 D2 D1 D0						D0
0A h	R/W		DELAY1 [3 : 0] DUTYMIN1 [3 : 0]						
Default	00 h	0	0 0 0 0 0 0 0					0	

D7-4 : DELAY1 [3 : 0] LED1 starting delay time setting

D3-0 : DUTYMIN1 [3 : 0] LED1 at Slope lighting minimum PWM Duty setting

Registe	r Name	LED1CNT3							
Address	R / W mode	D7	D7 D6 D5 D4 D3 D2 D1						D0
0B h	R/W		SLP1D1	[2 [3 : 0]		SLP1DT1 [3 : 0]			
Default	88 h	1	1 0 0 0 1 0						0

D7-4 : SLP1DT2 [3 : 0] LED1 slope lighting, the period of SLOPE operation 2 time

 $\mathsf{D3-0}:\mathsf{SLP1DT1}\;[3:0]\;\;\mathsf{LED1}\;\mathsf{slope}\;\mathsf{lighting},\;\mathsf{the}\;\mathsf{period}\;\mathsf{of}\;\mathsf{SLOPE}\;\mathsf{operation}\;\mathsf{1}\;\mathsf{time}$ 

Registe	r Name	LED1CNT4									
Address	R / W mode	D7	D7 D6 D5 D4 D3 D2 D1						D0		
0C h	R/W		SLP1DT4 [3 : 0]					SLP1DT3 [3 : 0]			
Default	88 h	1	1 0 0 0 1 0 0						0		

D7-4 : SLP1DT4 [3 : 0] LED1 slope lighting, the period of SLOPE operation 4 time D3-0 : SLP1DT3 [3 : 0] LED1 slope lighting, the period of SLOPE operation 3 time

Operation parameter of LED1 SLOPE operation will be set.

Please refer to following "4. LED control Slope lighting mode " for the details of slope operation.



#### 3. Register map details (continued)

DUTYMAX1 [3:0] correspond to the following PWM Duty setting as the following chart shows.

	DUTYMAX1 [3 : 0]				Duty setting for PWM operation [6 : 0]							
D3	D2	D1	D0	D6	D5	D4	D3	D2	D1	D0		
0	0	0	0	0	0	0	0	1	1	1		
0	0	0	1	0	0	0	1	1	1	1		
0	0	1	0	0	0	1	0	1	1	1		
0	0	1	1	0	0	1	1	1	1	1		
	-	-					~					
1	1	1	0	1	1	1	0	1	1	1		
1	1	1	1	1	1	1	1	1	1	1		

Duty setting for PWM operation [6:0]

[0000111]: 7 / 128 = 5.47 % [0001111]: 15 / 128 = 11.72 % [0010111]: 23 / 128 = 17.97 % [0011111]: 31 / 128 = 24.22 % : [1110111]: 119 / 128 = 92.97 % [1111111]: 127 / 128 = 99.22 %

DUTYMID1 [3: 0] correspond to the following PWM Duty setting as the following chart shows.

	DUTYMID1 [3 : 0]				Duty setting for PWM operation[6 : 0]							
D3	D2	D1	D0	D6	D5	D4	D3	D2	D1	D0		
0	0	0	0	0	0	0	0	0	0	0		
0	0	0	1	0	0	0	1	1	1	1		
0	0	1	0	0	0	1	0	1	1	1		
0	0	1	1	0	0	1	1	1	1	1		
	-	-					~					
1	1	1	0	1	1	1	0	1	1	1		
1	1	1	1	1	1	1	1	1	1	1		

Duty setting for PWM operation [6:0]

, ,	•	
[0000000] :	0 / 128 =	0 %
[0001111] :	15 / 128 =	11.72 %
[0010111] :	23 / 128 =	17.97 %
[0011111] :	31 / 128 =	24.22 %
:		
[1110111] :	119 / 128	= 92.97 %
[1111111] :	127 / 128	= 99.22 %



#### 3. Register map details (continued)

DUTYMIN1 [3 : 0] correspond to the following PWM Duty setting as the following chart shows.

	DUTYMIN1 [3 : 0]				Duty setting for PWM operation [6 : 0]							
D3	D2	D1	D0	D6	D5	D4	D3	D2	D1	D0		
0	0	0	0	0	0	0	0	0	0	0		
0	0	0	1	0	0	0	1	0	0	0		
0	0	1	0	0	0	1	0	0	0	0		
0	0	1	1	0	0	1	1	0	0	0		
	~	~					~					
1	1	1	0	1	1	1	0	0	0	0		
1	1	1	1	1	1	1	1	0	0	0		

Duty setting for PWM operation [6: 0]

[0000000] :	0 / 128 = 0 %
[0001000] :	8 / 128 = 6.25 %
[0010000] :	16 / 128 = 12.5 %
[0011000] :	24 / 128 = 18.75 %
:	
[1110000] :	112 / 128 = 87.5 %
[1111000] :	120 / 128 = 93.75 %

DELAY1 [3 : 0] is set as the following chart shows.

	DELAY	1 [3 : 0]		DLYSEL1 = 0	DLYSEL1 = 1
0	0	0	0	0.00 s	0.000 s
0	0	0	1	0.50 s	0.124 s
0	0	1	0	1.00 s	0.248 s
	~			~	~
1	1	1	0	7.00 s	1.736 s
1	1	1	1	7.50 s	1.860 s



#### 3. Register map details (continued)

SLP1DT1 [3 : 0] is set as the following chart shows.

	SLP1DT	1 [3 : 0]		Detention time at each step
0	0	0	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 1 = 53.3 $\mu$ s
0	0	0	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 1 = 4.0 ms
0	0	1	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 2 = 8.0 ms
	~			~
1	1	1	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 14 = 56.0 ms
1	1	1	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 15 = 60.0 ms

SLP1DT2 [3 : 0] is set as the following chart shows.

	SLP1DT	2 [3: 0]		Detention time at each step
0	0	0	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 1 = 53.3 $\mu$ s
0	0	0	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 1 = 4.0 ms
0	0	1	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 2 = 8.0 ms
	~			~
1	1	1	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 14 = 56.0 ms
1	1	1	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 15 = 60.0 ms

SLP1DT3 [3 : 0] is set as the following chart shows.

	SLP1DT	3 [3: 0]		Detention time at each step			
0	0	0	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 1 = 53.3 $\mu$ s			
0	0	0	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 1 = 4.0 ms			
0	0	1	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 2 = 8.0 ms			
	~			~			
1	1	1	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 14 = 56.0 ms			
1	1	1	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 15 = 60.0 ms			

SLP1DT4 [3 : 0] is set as the following chart shows.

	SLP1DT	4 [3: 0]		Detention time at each step					
0	0	0	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 1 = 53.3 $\mu$ s					
0	0	0	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 1 = 4.0 ms					
0	0	1	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 2 = 8.0 ms					
	~			~					
1	1	1	0	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 14 = 56.0 ms					
1	1	1	1	( PWM cycle = 53.3 $\mu$ s ) $\times$ 75 $\times$ 15 = 60.0 ms					



#### 3. Register map details (continued)

Registe	r Name		LED2CNT1									
Address	R / W mode	D7	D7 D6 D5 D4 D3 D2 D1						D0			
0D h	R/W		DUTYMA	X2 [3 : 0]		DUTYMID2 [3 : 0]						
Default	F8 h	1	1	1	1	1	0	0	0			

D7-4 : DUTYMAX2 [3 : 0] LED2 at slope lighting, maximum PWM Duty setting

D3-0 : DUTYMID2 [3 : 0] LED2 at slope lighting, middle PWM Duty setting

Registe	er Name		LED2CNT2									
Address	R / W mode	D7	D6	D5	D4	D3	D2	D1	D0			
0E h	R/W		DELAY	2 [3 : 0]		DUTYMIN2 [3 : 0]						
Default	00 h	0	0	0	0	0	0	0	0			

D7-4 : DELAY2 [3 : 0] LED2 starting delay time setting

D3-0 : DUTYMIN2 [3 : 0] LED2 at slope lighting, minimum PWM Duty setting

Registe	er Name		LED2CNT3								
Address	R / W mode	D7	D6	D5	D4	D3	D2	D1	D0		
0F h	R/W		SLP2D1	Г2 [3 : 0]		SLP2DT1 [3 : 0]					
Default	88 h	1	0	0	0	1	0	0	0		

D7-4 : SLP2DT2 [3 : 0] LED2 slope lighting, the period of SLOPE operation 2 time

D3-0 : SLP2DT1 [3 : 0] LED2 slope lighting, the period of SLOPE operation 1 time

Registe	er Name	LED2CNT4								
Address	R / W mode	D7	D6	D5	D4	D3	D2	D1	D0	
10 h	R/W		SLP2D1	F4 [3 : 0]		SLP2DT3 [3 : 0]				
Default	88 h	1	0	0	0	1	0	0	0	

D7-4 : SLP2DT4 [3 : 0] LED2 slope lighting, the period of SLOPE operation 4 time D3-0 : SLP2DT3 [3 : 0] LED2 slope lighting, the period of SLOPE operation 3 time

Operation parameter of LED2 SLOPE operation will be set.

Each parameter is the same as LED1 Parameter.

Please refer to following "4. LED control Slope lighting mode " for the details of slope operation.



#### 3. Register map details (continued)

Registe	er Name		LED3CNT1									
Address	R / W mode	D7	D7 D6 D5 D4 D3 D2 D1						D0			
11 h	R/W		DUTYMA	X3 [3 : 0]		DUTYMID3 [3 : 0]						
Default	F8 h	1	1	1	1	1	0	0	0			

D7-4 : DUTYMAX3 [3 : 0] LED3 at slope lighting maximum PWM Duty setting

D3-0 : DUTYMID3 [3 : 0] LED3 at slope lighting middle PWM Duty setting

Registe	er Name	LED3CNT2									
Address	R / W mode	D7	D6	D5	D4	D3	D2	D1	D0		
12 h	R/W		DELAY	3 [3 : 0]		DUTYMIN3 [3 : 0]					
Default	00 h	0	0	0	0	0	0	0	0		

D7-4 : DELAY3 [3 : 0] LED3 starting delay time setting

D3-0 : DUTYMIN3 [3 : 0] LED3 at slope lighting minimum PWM Duty setting

Registe	er Name		LED3CNT3								
Address	R / W mode	D7	D6	D5	D4	D3	D2	D1	D0		
13 h	R/W		SLP3D1	[2 [3 : 0]		SLP3DT1 [3 : 0]					
Default	88 h	1	0	0	0	1	0	0	0		

D7-4 : SLP3DT2 [3: 0] LED3 slope lighting, the period of SLOPE operation 2 time D3-0 : SLP3DT1 [3: 0] LED3 slope lighting, the period of SLOPE operation 1 time

Registe	r Name	LED3CNT4								
Address	R / W mode	D7	D6	D5	D4	D3	D2	D1	D0	
14 h	R/W		SLP3D	T4 [3: 0]		SLP3DT3 [3: 0]				
Default	88 h	1	0	0	0	1	0	0	0	

D7-4 : SLP3DT4 [3: 0] LED3 slope lighting, the period of SLOPE operation 4 time D3-0 : SLP3DT3 [3: 0] LED3 slope lighting, the period of SLOPE operation 3 time

Operation parameter of LED3 SLOPE operation will be set.

Each parameter is the same as LED1 parameter.

Please refer to following "4. LED control Slope lighting mode " for the details of slope operation.



#### 4. LED control

Constant current lighting mode

• It is possible to choose "Constant current lighting mode" and "Slope lighting mode" by setting Register LED\*MD. To operate at "Constant current mode", please set LED\*MD at "0". ( "\*" can be 1, 2, or 3.)



- Upon setting LED\*ON to "1", constant current operation will start after the previously set starting delay time, DELAY\*.
- As described in page 30, it is possible to turn on and off at High/Low of CLKPWM pin by making the external PWM operating mode for CLKPWM pin setting valid.



#### 4. LED control (continued)

Slope lighting mode

• To operate at "Slope lighting mode", please set LED\*MD at "1". ( "\*" can be 1, 2, or 3.)



- To repeat Slope operation from 1 to 4 after the previously set starting delay time, DELAY\*, please set Register LED\*ON at "1".
- The minimum resolution of SLOPE sequence control is 2.40 MHz reference clock cycle as below.





#### 4. LED control (continued)

1) Total time of Slope operation 1, 2

Total time of Slope operation 1, 2 can be controlled by SLP\*TT1[3 : 0]. SLP\*TT1[3 : 0] is set as described before.

- SLP\*TT1[3:0] setting has priority to the case of SLP\*TT1[3:0] < "SLOPE operation 1" + "SLOPE operation 2".</li>
- In case of that SLP\*TT1[3 : 0] time is over during SLOPE operation 1 (before SLOPE operation 2), SLOPE operation 2 is omitted and transferred to SLOPE operation 3 from the position of DUTYMAX.

2) Total time of Slope operation 3, 4

Total time of Slope operation 3, 4 can be controlled by SLP\*TT2[3: 0]. SLP\* TT2[3 : 0] is set as described before.

- SLP\*TT2[3 : 0] setting has priority to the case of SLP\*TT2[3 : 0] < "SLOPE operation 3" + "SLOPE operation 4".
- In case of that SLP\*TT2[3 : 0] time is over during SLOPE operation 3(before SLOPE operation 4), SLOPE operation 4 is omitted and transferred to SLOPE operation 1 from the position of DUTYMIN.

3) DUTYMIN, DUTYMID, DUTYMAX setting for SLOPE operation

SLOPE operation 1

PWM step increases step by step from the value set by DUTYMIN\*[3 : 0] to the value set by DUTYMID\*[3 : 0]. Please set the period by SLP\*DT1[3 : 0] for each step.

The value should be DUTYMIN\*[3 : 0] < DUTYMID\*[3 : 0].

SLOPE operation 1 operates at DUTYMIN = DUTYMID in case DUTYMIN\*[3 : 0]  $\geq$  DUTYMID\*[3 : 0] .

• SLOPE operation 2

PWM step increases step by step from the value set by DUTYMID\*[3 : 0] to the value set at DUTYMAX\*[3 : 0]. Please set the period by SLP\*DT2[3 : 0] for each step. The value should be DUTYMID\*[3 : 0] < DUTYMAX\*[3 : 0].

SLOPE operation 2 operates at DUTYMID = DUTYMAX in case DUTYMID\*[3 : 0]  $\geq$  DUTYMAX\*[3 : 0].

• Slope operation 3

PWM step decreases step by step from the value set by DUTYMAX\*[3 : 0] to the value set by DUTYMID\*[3 : 0]. Please set the period by SLP\*DT3[3: 0] for each step.

The value should be DUTYMID\*[3 : 0] < DUTYMAX\*[3 : 0].

SLOPE operation 3 operates at DUTYMID = DUTYMAX in case DUTYMID\*[3 : 0]  $\geq$  DUTYMAX\*[3 : 0] .

• SLOPE operation 4

PWM step decreases step by step from the value set by DUTYMID\*[3 : 0] to the value set by DUTYMIN\*[3 : 0]. Please set the period by SLP\*DT4[3 : 0] for each step.

The value should be DUTYMIN\*[3 : 0] < DUTYMID\*[3 : 0].

SLOPE operation 4 operates at DUTYMIN = DUTYMID in case DUTYMIN\*[3 : 0]  $\geq$  DUTYMID\*[3: 0] .



#### 4. LED control (continued)

4) External PWM operation mode of CLKPWM pin

The lighting synchronization with CLKPWM signal can be turned on by setting "External PWM operation mode" in register setting.

The maximum frequency which can be input to CLKPWM pin is 20 kHz.





Current waveform synchronized with CLKPWM pin



< At Slope lighting mode>





#### 4. LED control (continued)

5) External clock input mode and internal clock output mode of CLKPWM pin

The following configuration can be made up by choosing "External clock input mode", "Internal clock output mode" in register setting.

< Single application >



Unused state (CLKPWM operation OFF mode)



(Please refer to the explanation of the operation mode of P.17 for the setting of CLKPWM)

< External reference clock application >



(Please refer to the explanation of the operation mode of P.17 for the setting of CLKPWM)

Established : 2012-09-18 Revised : 2013-02-09



## PACKAGE INFORMATION (Reference Data)

## Package Code : XBGA012-W-1316AEL





#### **IMPORTANT NOTICE**

- 1. When using the LSI for new models, verify the safety including the long-term reliability for each product.
- 2. When the application system is designed by using this LSI, please confirm the notes in this book.
- Please read the notes to descriptions and the usage notes in the book.
- 3. Please use this product in compliance with all applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive. Our company shall not be held responsible for any damage incurred as a result of our IC being used by our customers, not complying with the applicable laws and regulations.
- 4. Pay attention to the direction of LSI. When mounting it in the wrong direction onto the PCB (printed-circuit-board), it might emit smoke or ignite.
- 5. Pay attention in the PCB (printed-circuit-board) pattern layout in order to prevent damage due to short circuit between pins. In addition, refer to the Pin Description for the pin configuration.
- 6. Perform a visual inspection on the PCB before applying power, otherwise damage might happen due to problems such as a solder-bridge between the pins of the semiconductor device. Also, perform a full technical verification on the assembly quality, because the same damage possibly can happen due to conductive substances, such as solder ball, that adhere to the LSI during transportation.
- 7. Take notice in the use of this product that it might be damaged or occasionally emit smoke when an abnormal state occurs such as output pin-VCC short (Power supply fault), output pin-GND short (Ground fault), or output-to-output-pin short (load short). Safety measures such as an installation of fuses are recommended because the extent of the above-mentioned damage and smoke emission will depend on the current capability of the power supply.
- 8. This IC is intended to be used for general electronic equipment.

Consult our sales staff in advance for information on the following applications: Special applications in which exceptional quality and reliability are required, or if the failure or malfunction of this IC may directly jeopardize life or harm the human body. Any applications other than the standard applications intended.

- (1) Space appliance (such as artificial satellite, and rocket)
- (2) Traffic control equipment (such as for automobile, airplane, train, and ship)
- (3) Medical equipment for life support
- (4) Submarine transponder
- (5) Control equipment for power plant
- (6) Disaster prevention and security device
- (7) Weapon
- (8) Others : Applications of which reliability equivalent to (1) to (7) is required

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9. This IC is neither designed nor intended for use in automotive applications or environments unless the specific product is designated by our company as compliant with the ISO/TS 16949 requirements.

Our company shall not be held responsible for any damage incurred by customers or any third party as a result of or in connection with the IC being used in automotive application, unless our company agrees to such application in this book. 10. Due to the unshielded structure of this LSI, functions and characteristics of the product cannot be guaranteed under the

- exposure of light. During normal operation or even under testing condition, please ensure that the LSI is not exposed to light.
- 11. Please ensure that your design does not have metal shield parts touching the chip surface as the surface potential is GND voltage.

12. Pay attention to the breakdown voltage of this LSI when using.

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• Special applications (such as for airplanes, aerospace, automotive equipment, traffic signaling equipment, combustion equipment, life support systems and safety devices) in which exceptional quality and reliability are required, or if the failure or malfunction of the products may directly jeopardize life or harm the human body.

It is to be understood that our company shall not be held responsible for any damage incurred as a result of or in connection with your using the products described in this book for any special application, unless our company agrees to your using the products in this book for any special application.

- (4) The products and product specifications described in this book are subject to change without notice for modification and/or improvement. At the final stage of your design, purchasing, or use of the products, therefore, ask for the most up-to-date Product Standards in advance to make sure that the latest specifications satisfy your requirements.
- (5) When designing your equipment, comply with the range of absolute maximum rating and the guaranteed operating conditions (operating power supply voltage and operating environment etc.). Especially, please be careful not to exceed the range of absolute maximum rating on the transient state, such as power-on, power-off and mode-switching. Otherwise, we will not be liable for any defect which may arise later in your equipment.

Even when the products are used within the guaranteed values, take into the consideration of incidence of break down and failure mode, possible to occur to semiconductor products. Measures on the systems such as redundant design, arresting the spread of fire or preventing glitch are recommended in order to prevent physical injury, fire, social damages, for example, by using the products.

(6) Comply with the instructions for use in order to prevent breakdown and characteristics change due to external factors (ESD, EOS, thermal stress and mechanical stress) at the time of handling, mounting or at customer's process. When using products for which damp-proof packing is required, satisfy the conditions, such as shelf life and the elapsed time since first opening the packages.

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